name

Put your answers on the paper provided. Please work neatly and staple your solutions, in problem order, to these two pages. Calculators are allowed; you must show your work for credit.

1. (8 pts.) What conditions must b_1 , b_2 , and b_3 satisfy in order for the following system to be consistent? Justify your answer.

- 2. (6 pts.) Set up a linear system to find a polynomial p(t) of degree 3 such that p(1) = 1, p(2) = 5, p'(1) = 2 and p'(2) = 9. Show your work.
- 3. (10 pts.) Suppose you are a spy watching the French coast guard (which is using a linear transformation to encode boat positions, as in our text.) You collect the following data: When the actual position is [5 42] they radio [89 52] and when the actual position is [6 41] they radio [88 53]. You may use a calculator for the computations on this problem, but explain your answers.
 - a. What is the coding matrix?
 - b. Suppose they radio [90 50]? What is the actual position?
- 4. (4 pts. each) Give the matrix that produces the following linear transformations from $\mathbb{R}^2 \to \mathbb{R}^2$. For each part, also give the matrix that produces the inverse transformation, or explain why no such inverse exists.
 - a. Reflection about the origin.
 - b. Counterclockwise rotation of $\pi/6$ radians.

c.
$$y_1 = x_1$$

 $y_2 = 0$

- d. Any shear parallel to the x axis.
- 5. (6 pts.) For an n by n matrix A, we call the linear system A x = 0 a homogeneous system. Prove: If x_1 and x_2 are solutions of a homogeneous linear system, then any linear combination of x_1 and x_2 is also a solution of the homogeneous system.
- 6. (8 pts.) Prove or disprove:
- a. The transformation S: $\mathbb{R}^2 \to \mathbb{R}^2$ given by $y_1 = 2x_1$ and $y_2 = 1$ is linear.
- b. The transformation T: $\mathbb{R}^2 \to \mathbb{R}^2$ given by $y_1 = x_1 + x_2$ and $y_2 = 0$ is linear.

a. If A and B are invertible n by n matrices, then AB=BA.
b. 0 1 is an elementary matrix. 1 0
c. For A and B invertible matrices, $(ABA^{-1})^4 = A B^4 A^{-1}$
d. Every elementary matrix is invertible.
e. Let $\text{proj}_L(\mathbf{v})$ be the projection of vector \mathbf{v} onto the line L and $\text{ref}_L(\mathbf{v})$ be the reflection of \mathbf{v} about L . Then $\text{ref}_L(\mathbf{v}) = 2 \text{ proj}_L(\mathbf{v}) - \mathbf{v}$.
f If A is an invertible 2 by 2 matrix such that $\mathbf{A}^2 = \mathbf{A}$, then A must be \mathbf{I}_2 .
g. A linear system with fewer unknowns than equations must have infinitely many solutions or none.
h. If vector \mathbf{u} is a linear combination of vectors \mathbf{v} and \mathbf{w} , then \mathbf{w} must be a linear combination of \mathbf{u} and \mathbf{v} .
8. (6 pts.) Suppose A is an invertible matrix with $A^{-1} = a$ b c d
and B is an invertible matrix with $B^{-1} = e$ g h .
Give the matrix for (AB) ⁻¹

- 9. (4 pts. each) Give an example that satisfies the following conditions. Explicitly demonstrate that your examples satisfy the given conditions. If the given conditions cannot be satisfied, say so and briefly explain why.
 - a. A non-homogeneous system of 3 equations and 3 unknowns that has an infinite number of solutions. (Give the solutions.)
 - b. An invertible 3 by 3 matrix A with two identical rows.
 - c. A 4 by 4 system with rank 2.
 - d. A matrix which maps the unit square in \mathbb{R}^2 to the square with corners (1 1), (2 1), (2 2) and (1 2).