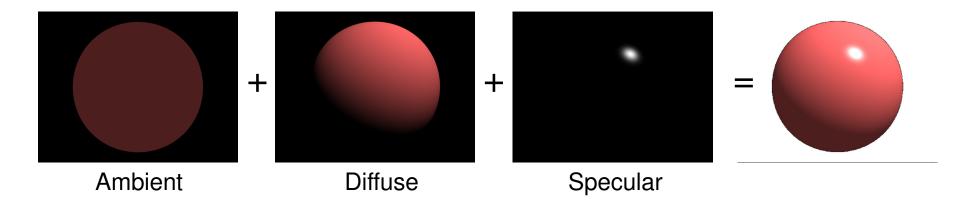
CSC 321 Computer Graphics

Polygon Shading

Review

- Local Illumination Model (1-hop reflection only)
 - Non-physical model: "looks good"
 - Ambient, diffuse and specular components



$$I = I_{amb} + I_{diff} + I_{spec}$$

$$= I_A k_a + I_L f_{att} (k_d (N \cdot L) + k_s (R \cdot V)^n)$$

Rendering Polygonal Models

Most scenes are modeled by polygons



Drawing A Polygon

- Compute location of polygon vertices on screen
 - Transformations
- See if the whole or part of the polygon is visible
 - Visibility culling
- Color each pixel in the visible part of the polygon
 - Polygonal shading
 - Texturing

Computing Polygon Vertices

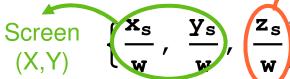
- Object and camera transform
 - Object transformation (obtained from a scene graph)
 - Transformation matrix for o3:

$$M = m2 m4 m5$$

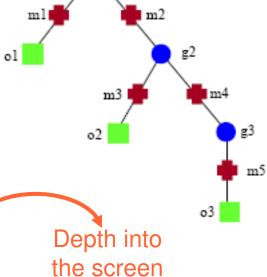
- Camera transformation
 - World-to-camera, perspective transform $C = D S_{xyz} S_{xy} R T$
- Combined:

$$\{x_s, y_s, z_s, w\} = CM\{x, y, z, 1\}$$

Normalized:



Depth into the screen



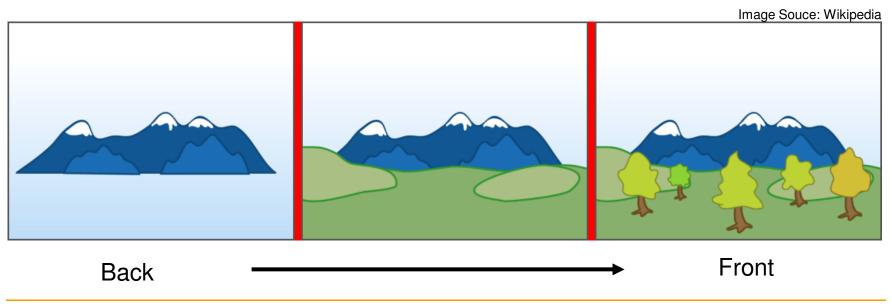
Visibility

- Is the polygon visible?
 - View-volume clipping: do not draw the polygon if it completely lies outside the view frustum
 - Clip against the 6 walls of the viewing volume
 - Back-face culling: do not draw the polygon if it faces "away" from the viewer.
 - Take the dot product of the polygon normal and the look vector.
 - If positive, the polygon is back facing and not drawn
 - Orientation of the polygon becomes critical
 - What about occlusion?

Occlusion culling

Painter's algorithm

- $\left\{\frac{x_s}{w}, \frac{y_s}{w}, \frac{z_s}{w}\right\}$ Depth into the screen
- Transform all polygons into screen coordinates
- Sort polygons by the minimum depth of its vertices
- Draw polygons from back to front



CSC 321

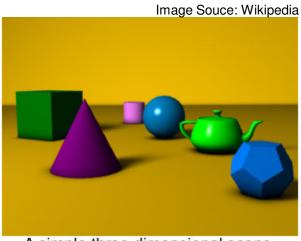
Painter's Algorithm

- Problem
 - Can not properly show intersecting/tangling polygons

Tangling: Intersecting: A B

Z-Buffer

- Z-buffer (depth buffer): an array storing the minimal depth at each pixel
 - After transformation, depth ranges from 0 (near plane) to 1 (far plane)
 - When multiple points projected onto a same pixel, only the point with a smaller depth is drawn.



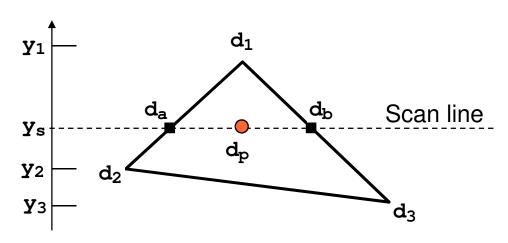
A simple three dimensional scene



Z-buffer representation

Z-Buffer

- Algorithm
 - Z-buffer Initialized to be 1 (far plane) for each pixel
 - Compute projected coordinates of the vertices and their depth
 - Scan-convert interior pixels of the polygon
 - Compute depth at each pixel by linear interpolation
 - Only draw the pixel (and update the z-buffer for that pixel) if the depth of the pixel is smaller than what's currently in the z-buffer



$$d_a = d_1 \frac{y_s - y_2}{y_1 - y_2} + d_2 \frac{y_1 - y_s}{y_1 - y_2}$$

$$d_b = d_1 \frac{y_s - y_3}{y_1 - y_3} + d_3 \frac{y_1 - y_s}{y_1 - y_3}$$

$$d_p = d_a \frac{x_b - x_p}{x_b - x_a} + d_b \frac{x_p - x_a}{x_b - x_a}$$

Better culling

Discard occluded triangles before projection

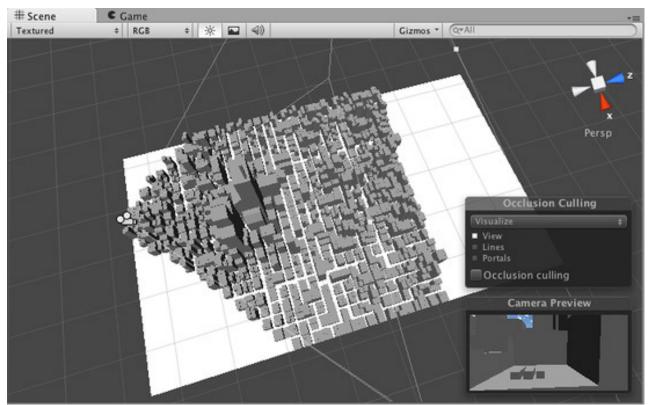


Image source: unity3d.com

Better culling

Discard occluded triangles before projection

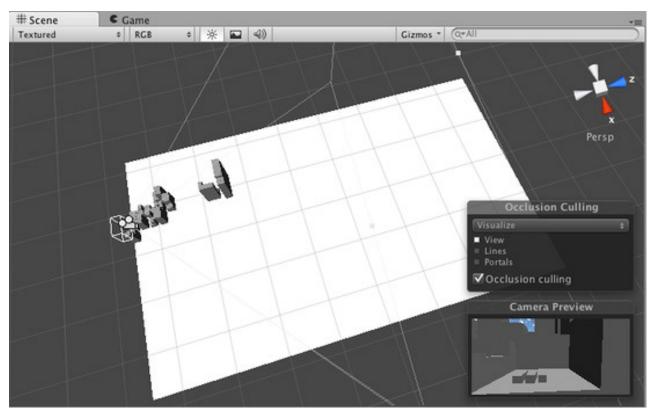


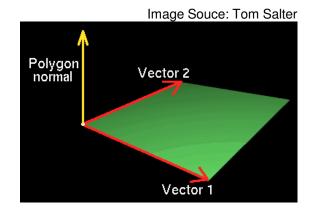
Image source: unity3d.com

Polygon Shading

- Using local illumination model (for efficiency)
 - Compute one color per polygon (flat)
 - Compute one color per vertex (Gouraud)
 - Compute one color for each pixel (Phong)

Flat Shading

- Use one color for each polygon
 - Pick any polygon vertex
 - Use the (normalized) cross-product of edge vectors as the normal
 - Compute local illumination
- Pros: Fastest
- Cons: Facet-looking
 - Discontinuity across edges





Gouraud Shading

- Compute the color at each vertex
 - Use the average normal of the incident polygons
- Blend the color within the polygon
 - Using linear interpolation

$$N_v = \frac{N_1 + N_2 + N_3 + N_4}{4}$$

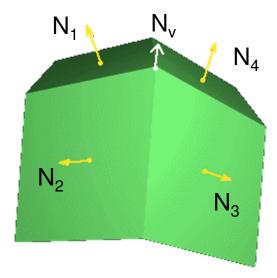
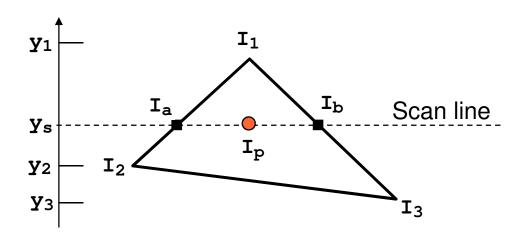


Image Souce: Tom Salter

Gouraud Shading

- Scan-line algorithm (similar to z-buffer):
 - Compute projected coordinates and color at each vertex
 - Scan-convert interior pixels of the polygon
 - Compute color at each pixel by linear interpolation



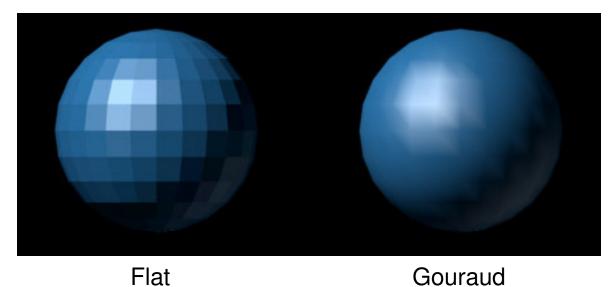
$$I_a = I_1 \frac{y_s - y_2}{y_1 - y_2} + I_2 \frac{y_1 - y_s}{y_1 - y_2}$$

Scan line
$$I_b = I_1 \frac{y_s - y_3}{y_1 - y_3} + I_3 \frac{y_1 - y_s}{y_1 - y_3}$$

$$I_p = I_a \frac{x_b - x_p}{x_b - x_a} + I_b \frac{x_p - x_a}{x_b - x_a}$$

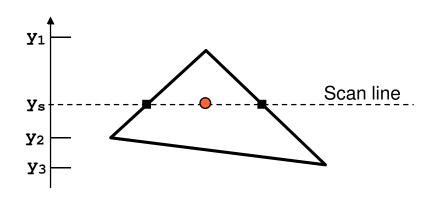
Gouraud Shading

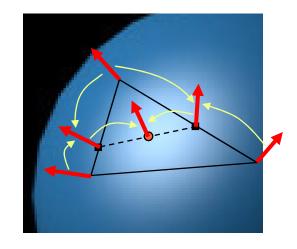
- Pros: Smoother looking than flat shading
 - Color continuous across edges
- Cons
 - Patchy, because color is not smooth (or *derivative* not continuous)
 - Details (e.g., highlight) missing within a polygon



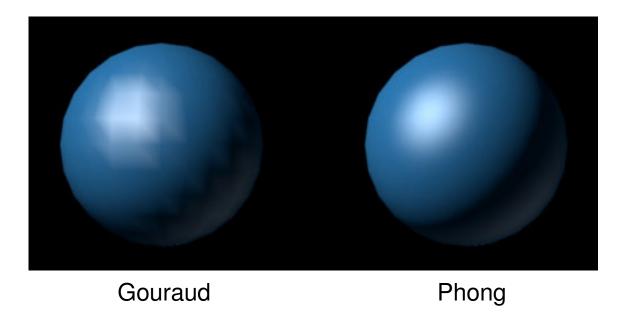
··· C

- Using smoothly varying normals
 - Compute a normal for each scan-converted pixel
 - Linear interpolation of normals at the vertices (using scan-line)
 - Compute illumination
 - Using the interpolated normal and the location of the 3D point



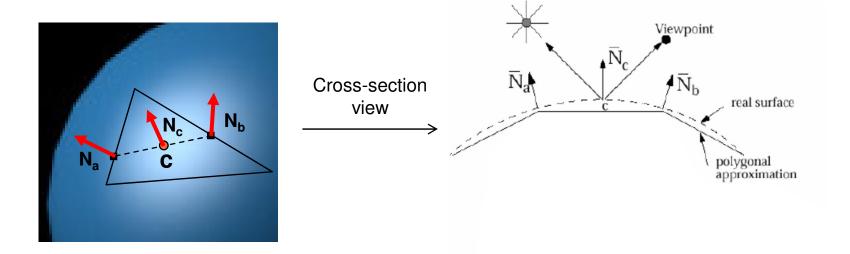


- Pros:
 - Smoother ("Faking" a smooth surface)



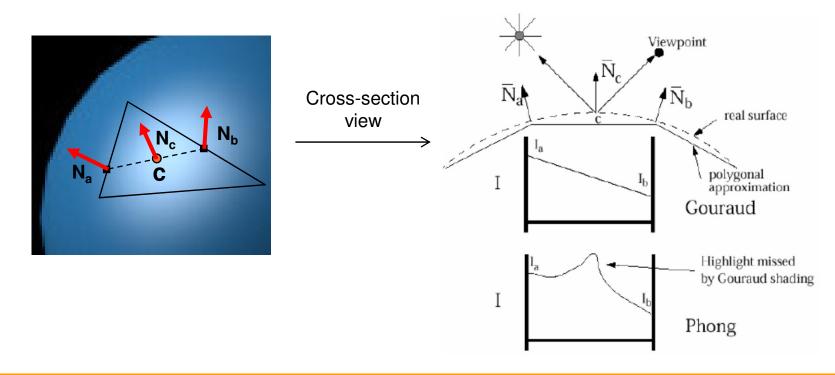
• Pros:

- Smoother ("Faking" a smooth surface)
- Capturing specular lighting inside the polygon



• Pros:

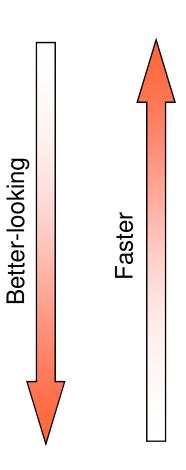
- Smoother ("Faking" a smooth surface)
- Capturing specular lighting inside the polygon



- Pros:
 - Smoother ("Faking" a smooth surface)
 - Capturing specular lighting inside the polygon
- Cons: much slower
 - OpenGL does not implement Phong

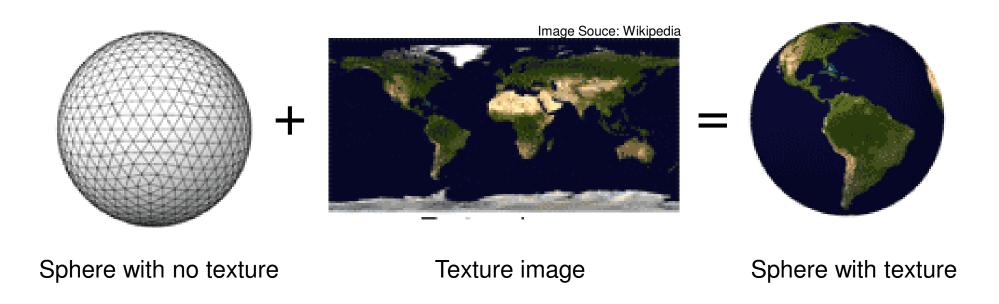
Summary

- Flat shading
 - Compute local illumination once per polygon
- Gouraud shading
 - Compute local illumination once per vertex
 - Interpolate color across the polygon
- Phong shading
 - Interpolate normal across the polygon
 - Compute local illumination per pixel



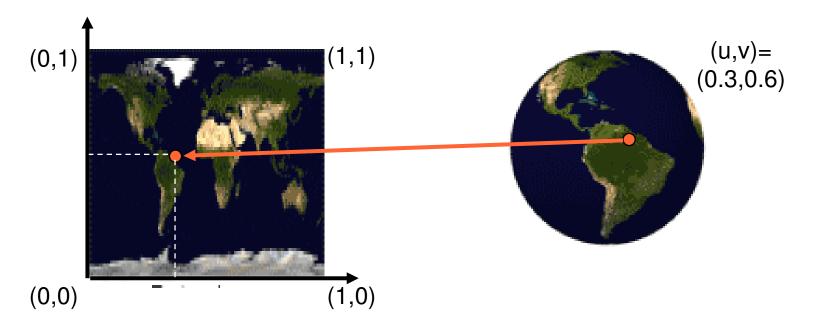
Texture

Simple, effective approach for adding surface detail



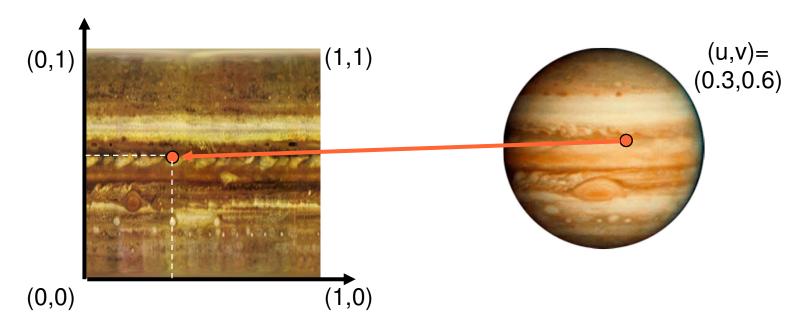
Texture Coordinates

- Uses two parameters (u,v)
 - Each object point is associated with a pair (u,v) between 0 and 1
 - Given a texture image in the unit square, the object point is shaded using the color at (u,v) on the texture image



Texture Coordinates

- Uses two parameters (u,v)
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Texture Mapping

- Find a texture image (the easy part)
- Get texture coordinates for each point on the model (the hard part)
 - First, find texture coordinates for each polygon vertex
 - Parameterization
 - Interpolate texture coordinates within each polygon
 - Using scan-line algorithm

Mapping a Cylinder

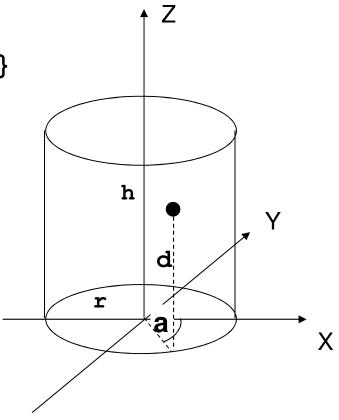
Cylindrical parameterization

$$p[d, \alpha] = \{rCos[\alpha], rSin[\alpha], d\}$$

 $0 \le d \le h, 0 \le \alpha < 2\pi$

Normalize d, a to correct range.

$$u = \frac{\alpha}{2\pi}, v = \frac{d}{h}$$



Mapping a Sphere

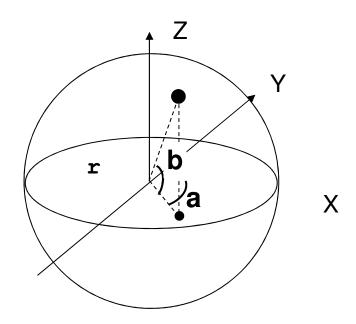
Longitude-latitude parameterization

$$p[\alpha, \beta] = \{r Cos[\beta] Cos[\alpha], r Cos[\beta] Sin[\alpha], r Sin[\beta]\}$$

$$0 \le \alpha < 2\pi, \frac{-\pi}{2} \le \beta \le \frac{\pi}{2}$$

Normalize a, b to correct range

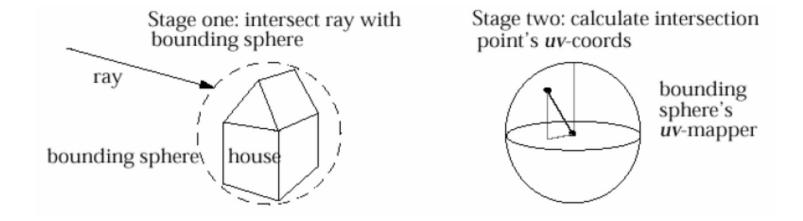
$$u = \frac{\alpha}{2\pi}, v = \frac{\beta + \pi/2}{\pi}$$



What about arbitrary shapes?

- Mapping to a sphere
 - Wrap the object in a sphere
 - Use the u,v parameter of the projected point on the sphere



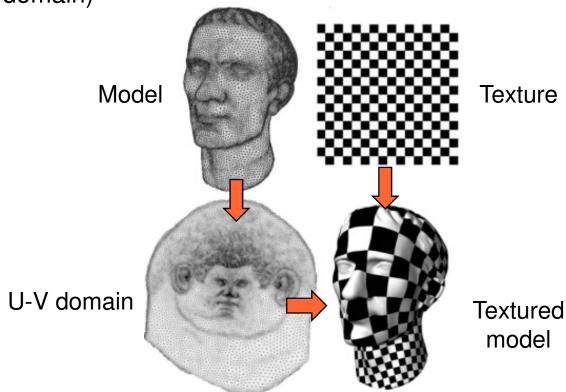


What about arbitrary shapes?

Global parameterization

- Minimizing distortions (e.g., preserving triangle angles or areas in the

UV domain)



What about arbitrary shapes?

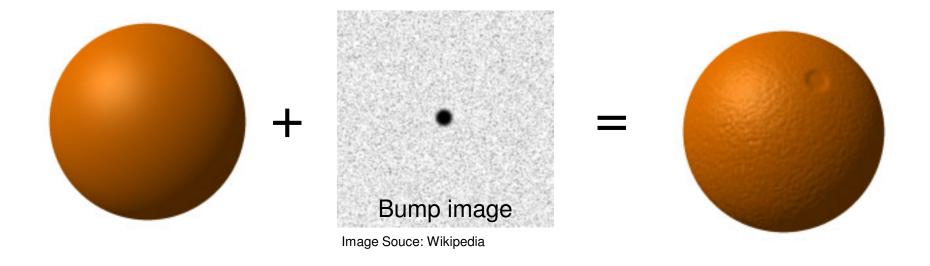
- Using a texture atlas
 - Cut the shape into different patches (manually or automatically) and compute U,V coordinates for each patch
 - Give one texture image for each patch
 - Often used for characters/animals in games





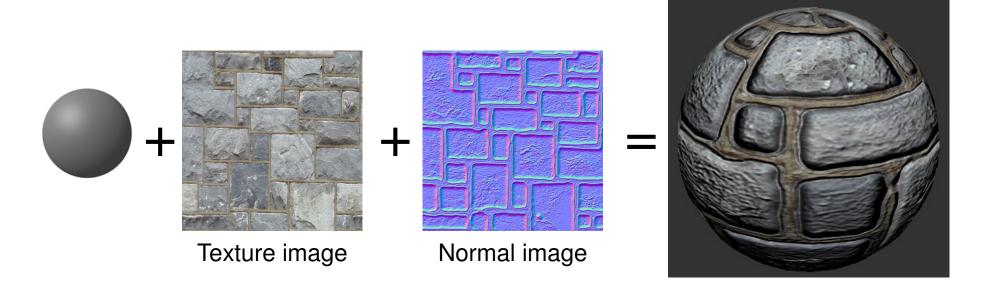
Bump Mapping

- "Fake geometry" by varying surface normal
 - The map encodes height variation (as grayscale), from which the normal can be computed
 - Needs Phong shading to compute per-pixel lighting



Normal Mapping

- "Fake geometry" by defining new normal at each point
 - Encodes actual normal (X,Y,Z as R,G,B)



Bump & Normal Mapping

Limitation: cannot change the silhouette of the shape

